

# Tips, Tricks, and Techniques for Theoretical Computer Science

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## 1 Non-Probabilistic Inequalities and Approximations

**Exponential function.** For all  $x$ ,

$$1 + x \leq e^x.$$

Easily following are e.g.  $1 - x \leq e^{-x}$ , or  $(1 + x)^c \leq e^{cx}$ , or  $(1 + \frac{1}{x})^c \leq e^{c/x}$ , etc.

It follows that  $(1 + 1/k)^k \leq e$ , and for  $k > -1$  we also have the upper-bound  $(1 + 1/k)^{k+1} \geq e$ . Also (and the inequality reverses for negative  $x$ ),

$$e^{-x} \leq 1 - x + \frac{x^2}{2} \quad (\text{for } x \geq 0).$$

Follows from Taylor's Theorem, as we have  $e^{-x} = 1 - x + \frac{x^2}{2} + R$  where  $R \leq 0$ . See the Taylor series and Taylor's Theorem for  $e^x$ .

**Logarithm.** For all  $x \geq 0$ ,

$$x - \frac{x^2}{2} \leq \ln(1 + x) \leq x.$$

You can push this as far as you want with the Taylor expansion, e.g.

$$x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} \leq \ln(1 + x) \leq x - \frac{x^2}{2} + \frac{x^3}{3}.$$

**Cosh.** The hyperbolic cosine function is  $\cosh(x) = \frac{1}{2}e^x + \frac{1}{2}e^{-x}$ . For all  $x$ ,

$$\frac{1}{2}e^x + \frac{1}{2}e^{-x} \leq e^{x^2/2}.$$

**Bernoulli's Inequality.** For all  $x \geq -1$ , and  $n \leq 0$  or  $n \geq 1$ ,

$$1 + xn \leq (1 + x)^n.$$

For  $0 < n < 1$ , the inequality is reversed.

See also the Binomial expansion of  $(1 + x)^n$  when  $n$  is an integer.

**Stirling's Approximation for the factorial.** The factorial satisfies

$$\left(\frac{n}{e}\right)^n \leq n! \leq n^n.$$

As  $n \rightarrow \infty$ , Stirling's approximation says that

$$n! \approx \sqrt{2\pi n} \left(\frac{n}{e}\right)^n.$$

This is quite tight; in fact we have[1]

$$\sqrt{2\pi n} \left(\frac{n}{e}\right)^n e^{\frac{1}{12n+1}} \leq n! \leq \sqrt{2\pi n} \left(\frac{n}{e}\right)^n e^{\frac{1}{12n}}.$$

**Binomial coefficients.** The binomial coefficient " $n$  choose  $k$ " is

$$\binom{n}{k} = \frac{n!}{(n-k)!k!},$$

and we have

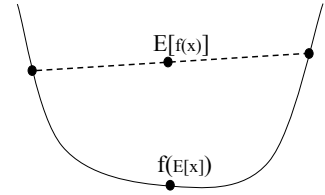
$$\left(\frac{n}{k}\right)^k \leq \binom{n}{k} \leq \left(\frac{ne}{k}\right)^k.$$

**Jensen's Inequality.** Suppose  $f$  is convex: for  $\alpha \in (0, 1)$ ,  $f(\alpha x + (1 - \alpha)y) \leq \alpha f(x) + (1 - \alpha)f(y)$ . Then for any random variable  $X$ ,

$$f(\mathbb{E} X) \leq \mathbb{E} f(X).$$

In particular, for positive  $\{a_i\}$ ,

$$f\left(\frac{\sum a_i x_i}{\sum a_i}\right) \leq \frac{\sum a_i f(x_i)}{\sum a_i}.$$



For concave functions, all inequalities are reversed.

**$p$ -norm Inequalities.** The  $\ell_p$  norm, for  $1 \leq p$ , of a vector  $x \in \mathbb{R}^d$  is  $\|x\|_p = \left(\sum_{j=1}^d |x_j|^p\right)^{1/p}$ . The  $\ell_\infty$  norm is  $\max_j |x_j|$ . For  $1 \leq p \leq r \leq \infty$ ,

$$\begin{aligned} \|x\|_r &\leq \|x\|_p \\ \|x\|_p &\leq d^{\frac{1}{p} - \frac{1}{r}} \|x\|_r \end{aligned}$$

where  $\frac{1}{\infty} = 0$ . (In this setting, there's no difference between  $L_p$  and  $\ell_p$ .)

The first inequality is tight for  $x = \alpha(0, \dots, 0, \pm 1, 0, \dots, 0)$ ; the second for  $x = \alpha(\pm 1, \dots, \pm 1)$ .

## 2 Probabilistic Inequalities and Bounds

**Union Bound.** For any events  $A_1, A_2, \dots$  (no matter how correlated),

$$\Pr[A_1 \text{ or } A_2 \text{ or } \dots] \leq \Pr[A_1] + \Pr[A_2] + \dots.$$

If each  $A_i$  has probability  $p$ , and there are  $n$  of them, then the union bound gives  $np$ . If you think they behave approximately independently, then the true probability should be about  $1 - (1 - p)^n \approx np - O((np)^2)$ . (Using that the Binomial expansion of  $(1 - p)^n$  is  $1 - np + \binom{n}{2}p^2 - \dots$ .)

**Markov's Inequality.** Let  $X$  be a nonnegative real-valued random variable. Then

$$\Pr[X \geq a] \leq \frac{\mathbb{E}[X]}{a}.$$

This is especially useful when both quantities are very small, e.g.  $\mathbb{E}[X] \rightarrow 0$  and we want to bound  $\Pr[X \geq 1]$ .

**Chebyshev's Inequality.** Let  $Y$  be a real-valued random variable. By applying Markov's to the variable  $X = |Y - \mathbb{E}[Y]|^2$ , we can get

$$\Pr[|Y - \mathbb{E}[Y]| \geq b] \leq \frac{\text{Var}(Y)}{b^2}.$$

**Chernoff Bound for Binomials.** Let  $X \sim \text{Binomial}(m, p)$  (that is, the number of heads in  $m$  independent coin flips with probability  $p$  each). Then

$$\Pr[X \leq k] \leq e^{-(mp-k)^2/2mp}.$$

(Of course,  $mp$  is the expected number of heads.) Put another way,

$$\Pr[X \leq mp - c\sqrt{mp}] \leq e^{-c^2/2}.$$

You can get a tail bound both above and below: For  $k \leq mp$ ,

$$\Pr[|X - mp| \geq k] \leq 2e^{-k^2/3mp}.$$

A useful reference is Mitzenmacher and Upfal [2].

**Hoeffding's Inequality.** Essentially a generalization of the above. Let  $X_1, \dots, X_m$  be i.i.d. with each  $X_i$  supported on an interval of size  $b_i$ ; let  $S = \sum_i X_i$ . Then

$$\Pr[|S - \mathbb{E}[S]| \geq k] \leq 2e^{-2k^2/\sum_i b_i^2}.$$

**Tail bounds in terms of  $\delta$ .** A useful restatement of Hoeffding's is as follows. Let each  $b_i = 1$  for simplicity. If we let  $k = |S - \mathbb{E}[S]|$ , then with probability at least  $1 - \delta$ ,

$$k \leq \sqrt{\frac{m}{2} \ln(2/\delta)}.$$

Such rephrasing can come from any Chernoff-style tail bound and is common in e.g. PAC learning.

**Chernoff+Union and  $\log(n)$ .** Suppose (for concreteness) we have  $n$  Binomials( $m, p$ ) and we want to claim that with probability  $1 - \delta$ , all of them are at most a distance  $k$  from their expectation. We can show (notice the new factor of  $\log(n)$ )

$$k \leq \sqrt{\frac{m}{2} \ln(n/\delta)}$$

because by Chernoff or Hoeffding, each of the  $n$  Binomials is within  $k$  of its expectation with probability at least  $1 - \frac{\delta}{n}$ , so by a union bound over the  $n$  of them, the probability that any one differs by more than  $k$  is bounded by  $\delta$ .

Note we did not need independence for the union bound. Because of this phenomenon, one often sees the phrasing that a union bound "adds a factor of  $\log(n)$ ".

### 3 More “Advanced” Probabilistic Inequalities

**Subgaussianity.** If  $X$  has mean zero and is  $\lambda^2$ -subgaussian, meaning  $\mathbb{E} e^{\theta X} \leq e^{\theta^2 \frac{\lambda^2}{2}}$  for all  $\theta > 0$ , then by the Chernoff method

$$\begin{aligned} \Pr[X \geq t] &\leq \frac{\mathbb{E} e^{\theta X}}{e^{\theta t}} \\ &\leq e^{\theta^2 \frac{\lambda^2}{2} - \theta t} \\ &\leq e^{-t^2/(2\lambda^2)} \end{aligned}$$

by choosing  $\theta = t/\lambda^2$ .

$X$  also has variance at most  $\lambda^2$ . If  $X$  and  $Y$  are  $\lambda_1^2$  and  $\lambda_2^2$ -subgaussian, respectively, then  $\alpha X + \beta Y$  is  $(\alpha^2 \lambda_1^2 + \beta^2 \lambda_2^2)$ -subgaussian, since  $\mathbb{E} e^{\theta(\alpha X + \beta Y)} = \mathbb{E} e^{\theta \alpha X} \mathbb{E} e^{\theta \beta Y}$ , etc. A normal( $0, \sigma^2$ ) is  $\sigma^2$ -subgaussian, any centered variable with  $|X| \leq \lambda$  is  $\lambda^2$ -subgaussian, and a Binomial( $n, p$ ) minus its mean, being the sum of  $n$  centered Bernoullis which are each 1-subgaussian, is  $n$ -subgaussian.

**McDiarmid’s Inequality.** Let  $X_1, \dots, X_n$  be independent and write  $\vec{X} = (X_1, \dots, X_n)$ . If  $f(\vec{X})$  has *sensitivity*  $c$ , i.e. if for all  $\vec{X}, \vec{X}'$  identical except for a single  $X_i$ ,

$$|f(\vec{X}) - f(\vec{X}')| \leq c,$$

$$\text{then } \Pr \left[ \left| f(\vec{X}) - \mathbb{E} f(\vec{X}) \right| \geq t \right] \leq e^{-2t^2/(nc^2)}.$$

**Martingales and Azuma’s.** The variables  $X_1, \dots, X_n$  form a *martingale* if each  $\mathbb{E}[X_i | X_1, \dots, X_{i-1}] = X_{i-1}$ , for example, a random walk. If it satisfies bounded differences, i.e.  $|X_i - X_{i-1}| \leq c$  for all  $i$  with probability 1, then Azuma’s inequality states

$$\Pr [X_n - \mathbb{E} X_n \geq t] \leq e^{-t^2/(2nc^2)}.$$

## 4 Geometric and Random Phenomena

**Balls-in-bins, Birthday, Coupons.** Consider throwing  $m$  balls uniformly at random into  $n$  bins.

(1) The *birthday paradox* says that, once  $m \geq \Theta(\sqrt{n})$ , we expect some bin to contain at least two balls (a “collision”). This follows because any pair of balls has a  $\frac{1}{n}$  chance of colliding and there are  $\binom{m}{2}$  pairs of balls, giving the expected number of collisions  $\binom{m}{2} \frac{1}{n}$ .

(2) When  $m = n$ , the max-loaded bin has with very good probability a load of  $O(\log n / \log(\log n))$ .

(3) The *coupon-collector’s problem* asks how many balls must be thrown before every bin receives at least one ball. The answer is  $O(n \log n)$ , as follows. When  $k$  bins are empty, the expected time to fill one of them is  $\frac{n}{k}$ , so the expected number of balls needed is  $\frac{n}{n} + \frac{n}{n-1} + \dots + \frac{n}{1} = n \sum_{k=1}^n \frac{1}{k} = nH_n$ , where  $H_n$  is called the  $n$ th harmonic number, which is on the order of  $\log(n)$ .

**High-dimensional Cubes.** The unit hypercube in  $\mathbb{R}^d$  has vertices  $\{0, 1\}^d$ . It has volume 1, but the distance between two opposite vertices (e.g.  $(0, \dots, 0)$  and  $(1, \dots, 1)$ ) is  $\sqrt{d} \rightarrow \infty$  as  $d$  increases. It is often helpful to visualize the “Boolean hypercube” (the set of vertices of the hypercube) as a sequence or stack of horizontal layers, where each horizontal “slice” is the set of vertices that have  $k$  coordinates equal to 1 and  $d - k$  coordinates equal to 0, with the “top” ( $k = 0$ ) layer containing only  $(0, \dots, 0)$  and the “bottom” ( $k = d$ ) layer containing only  $(1, \dots, 1)$ ; the middle layer contains  $\binom{d}{2}$  vertices.

**High-dimensional Spheres.** The unit sphere in  $\mathbb{R}^d$  is the set of points at Euclidean distance one from the origin. The volume of the enclosed ball is  $\frac{\pi^{d/2}}{\Gamma(1+d/2)}$ , where  $\Gamma$  is the generalization of the factorial function to real numbers with  $\Gamma(1+x) = x!$  if  $x$  is an integer. In particular, the volume approaches zero as  $d \rightarrow \infty$ , although the radius is a constant 1.

A sphere of radius 0.5 centered in the unit cube will touch the center of every face of the cube, yet encloses a volume rapidly approaching zero as  $d$  grows (fills almost none of the cube). It may be helpful to visualize the  $d$ -dimensional sphere as a “spiky” body with little volume but reaching out in every dimension.

**The “Spherical Shell” in High Dimensions.** For random vectors with independent coordinates, we often expect concentration in a spherical “shell” at a certain distance from the origin. For instance, suppose we choose a point in  $\mathbb{R}^d$  by picking each coordinate  $X_i$  in  $\{0, 1\}$  uniformly and independently. The squared distance to the origin is  $\sum_{i=1}^d X_i^2 = \sum_{i=1}^d X_i$ , which by the Chernoff bound for Binomials is highly concentrated around  $\frac{d}{2}$ ; in other words, the distance to the origin is concentrated near  $\sqrt{d/2}$ , which is to say most of the probability lies in a spherical shell.

## 5 Proof Techniques

**Iterated Expectations.** *The expected value of  $X$  is the expected value, over all values of  $Y$ , of the expected value of  $X$  given  $Y$ .*

$$\mathbb{E}_X X = \mathbb{E}_Y \left[ \mathbb{E}_{X|Y} X \right].$$

This allows computing the expected value of  $X$  “indirectly” by marginalizing over  $Y$ .

**Minimax (“Yao’s Principle”).** *The best deterministic algorithm for a fixed input distribution beats any randomized algorithm on a worst-case input.* Let  $\mathcal{A}$  be a randomized algorithm (that is, distribution over deterministic algorithms) and let  $\mathcal{X}$  be a distribution over inputs. Then

$$\max_{\text{deterministic algos } a} \mathbb{E} \text{ performance}(a, \mathcal{X}) \geq \min_{\text{inputs } x} \mathbb{E} \text{ performance}(\mathcal{A}, x).$$

This is good for showing lower bounds, like “no randomized algorithm has an approximation factor better than  $c$ ”. To prove this, you can construct a distribution over inputs and show that every deterministic algorithm does worse than  $c$  on this distribution.

**Principle of Deferred Decisions.** If you have a randomized algorithm or are e.g. building a randomized graph, avoid constructing or reasoning about realizations of a particular piece until your algorithm/analysis touches it. For example, when traversing a random graph, you don’t need to reason about the probability of all possible realized graphs, just realizations of the nodes and edges your traversal touches.



## References

- [1] Herbert Robbins, *A Remark on Stirling's Formula*, The American Mathematical Monthly, 1955.
- [2] Michael Mitzenmacher and Eli Upfal, *Probability and Computing: Randomized Algorithms and Probabilistic Analysis*, Cambridge University Press, 2005.